

Industria, Innovazione e Ricerca: Le nuove frontiere del volo a pilotaggio remoto

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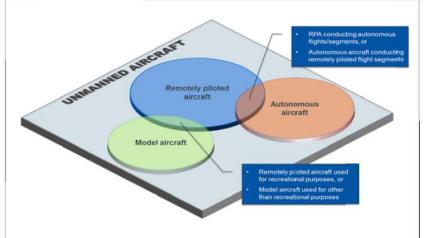
University of Naples Federico II, June, 12<sup>th</sup>, 2015



# **Fundamental Principle**



- Unmanned Aircraft is a powered, aerial vehicle that does not carry a human operator, can fly **autonomously** or be **piloted remotely**.
- **Remotely Piloted Aircraft System (RPAS)** is a type of UAS and is the only one in the rulemaking process ICAO for civil integration.



• **RPAS** or fully autonomous or combination are subject to art. 8 ICAO "No aircraft capable of being flown without a pilot shall be flown <u>without a pilot</u> over the territory of a contracting State without <u>special authorization</u> by that State and in accordance with the terms of such authorization. Each contracting State undertakes to insure that the flight of such aircraft without a pilot in regions open to civil aircraft <u>shall be so controlled</u> as to obviate danger to civil aircraft."

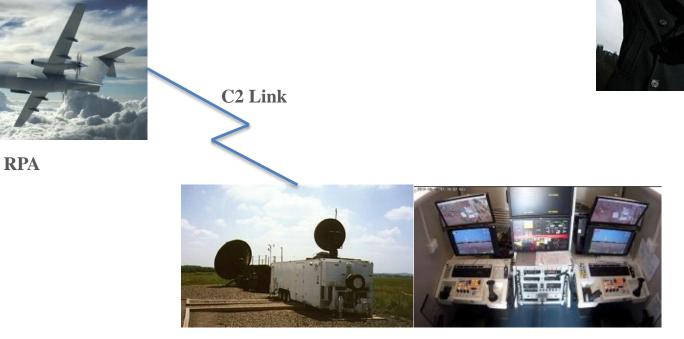
#### **RPAS** as a System



- RPAS is a system composed by:
  - A Remotely Piloted Aircraft (RPA).
  - A Remote Pilot Station(s) (RPS).
  - Command&Control (C2) Link.







RPS

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# Authorization Effort based on ConOPS and

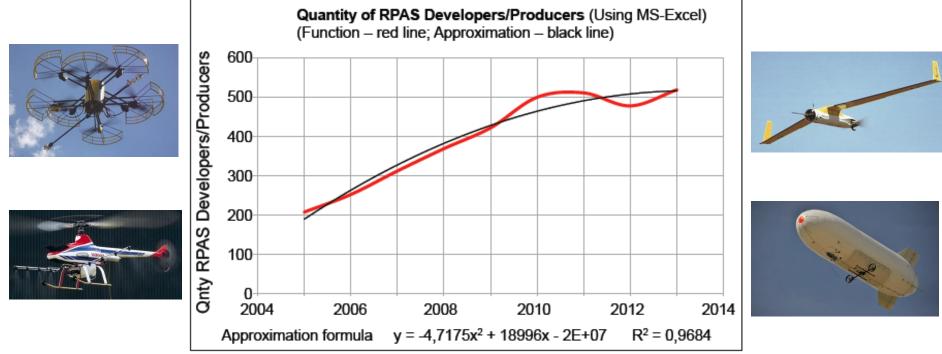
#### MTOM

***	Where the EU is Going									
* <b>RPAS</b> * * * *	COMMERCIAL & NON-COMMERCIAL OPERATIONS									
		RPAS Operator Certificate Obligatory								
RPA MTOM	< 150 kg				> 150 kg					
Flight Altitude	Very Low Level < 500 ft				Above > 500 ft AGL					
Flight	<b>T</b> -41- V		Е	в	Tath	VFR		IFR		
Density Population	Teth	VLOS	VLOS	VLOS	Teth	EVLOS	BVLOS	RLOS	BRLOS	
Unpopulated (remonte agricultural, over sea, or fenced off) Lightly Populated Highly	Declaration signed by RPAS Operator, RPAS Safety Assessment, Pilot Approval by accredited <b>Qualified Entity</b> (contracted by the Operator)			Type Certicate based on « Common Rules » but issued by NAAs: • Language • Proximity • Fees Proportionate Rules			ICAO scope International Flights Type Certificate Issued by EASA			
Populated	JARUS (CS-LURS, 1309, ORG etc.)									

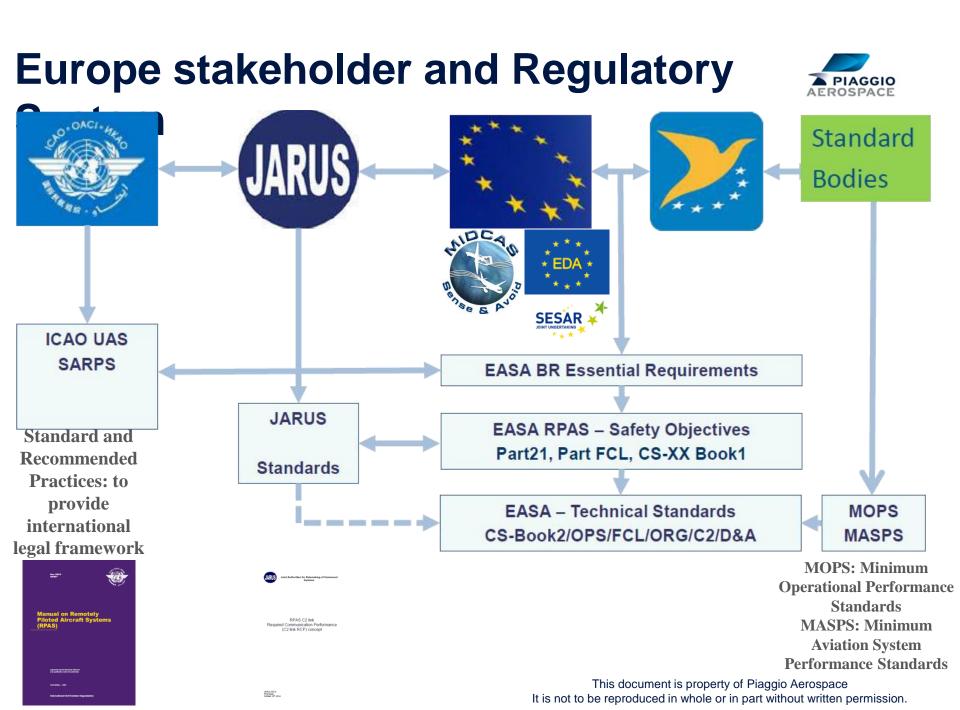
# **VLL Developing Activities**



• Fast developing activity in particular for VLL < 150 Kg with multiple applications.



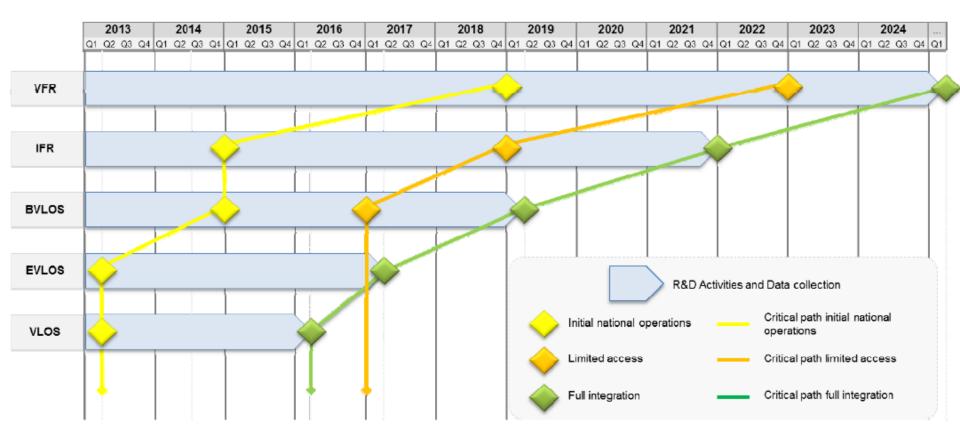
- In EASA Countries:
  - 2495 operators, 114 RPAS manufacturers. Very small to small RPAS with a maximum take-off mass below 150kg.
  - 16 Countries have national rules, 11 are preparing rules but they are not harmonised. This document is property of Piaggio Aerospace It is not to be reproduced in whole or in part without written permission.



#### **ERSG Roadmap**



• ERSG (European RPAS Steering Group) aims at developing a European civil RPAS integration Roadmap (Regulatory, R&D, Complementary).



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## **Technologies for RPAS**

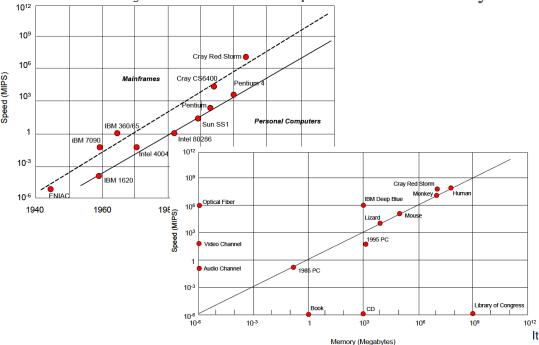


- To compensate for the absence of an onboard pilot enabling unmanned flight, the basic approaches to implementing unmanned flight (autonomy and pilotin-the-loop) rely predominantly on:
  - Processor Technologies.
  - Communication Technologies.
  - Detect&Avoid.
- Other technologies to develop for future RPAS are:
  - Platform Technologies.
  - Payload Technologies.

#### **Processor Technology**



- RPAS, due to the high level of functionalities required (e.g. ATOL, Traffic and Ground Collision Avoidance etc.), need to use a Vehicle Control Management System (VCMS) instead of a "limited" Flight Control Computer (FCC).
- To enhance autonomous capability of RPAS, computer's processors technology allowing faster computations, higher memory capacity, and safe responses (algorithms) are needed.
- Most of processing activities are onboard, so computers' size, weight, reliability, integrity and dissimilarity for high level of safety are critical issues.
- Rely on commercial processor driven by safety-critical aeronautical specification.



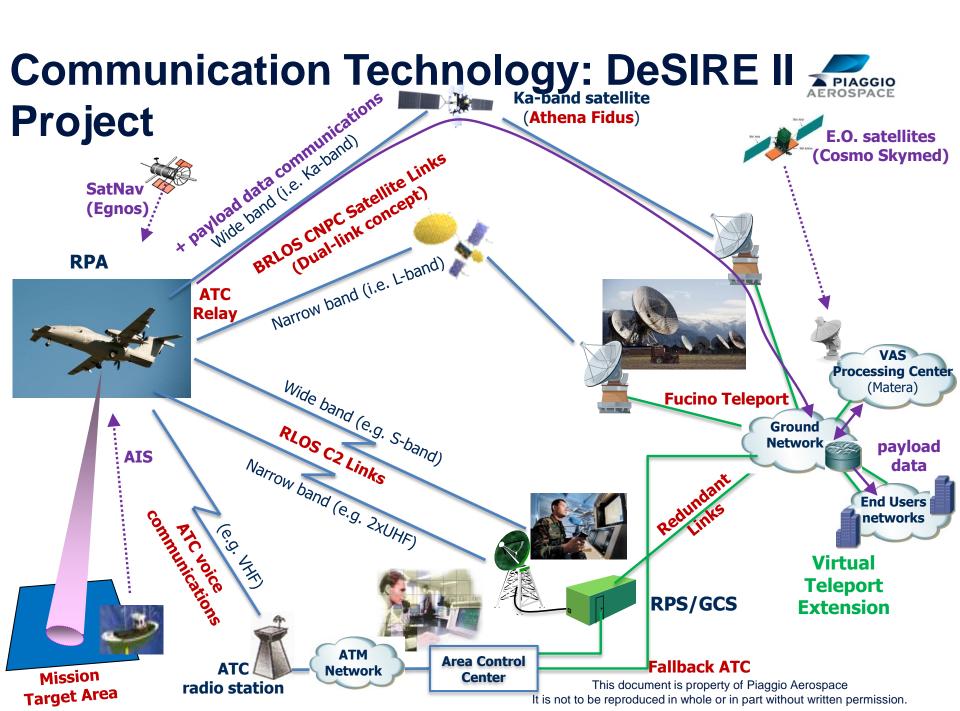


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## **Communication Technology**



- Airborne data link rates and processor speeds are in a race to enable future RPAS capabilities.
- Data rates are limited by usable spectrum and by the requirement to minimize airborne system size, weight, and power (SWAP).
- Congestion of S, C and L bands: 1.5 bps/Hz, close to theoretical maximum of 1.92.
- Rely on commercial markets (wireless communications, airliner links, finance) to drive link modulation methods technology, increasing the power of higher frequency (Ka), thus decreasing size, and weight.



## **Detect&Avoid (DAA)**

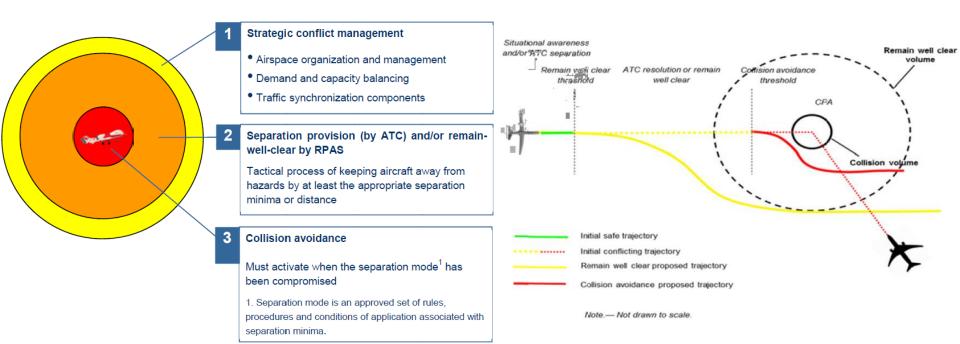


- DAA is "the capability to see, sense or detect conflicting traffic or other hazard and take appropriate action".
- This capability aims to ensure a safe integration of RPAS flight and enable full integration in all airspace classes.
- DAA capabilities are required for RPAS to limit risks of following hazards:
  - Conflicting traffic.
  - Terrain and obstacles.
  - Hazardous meteorological conditions.
  - Ground operations.
  - Other airborne hazards, including wake turbulence, wind shear etc..
- Major challenge for RPAS, due to the fact that current DAA systems and procedures of manned aviation cannot be used for RPAS (TCAS, Weather Radar, TAWS etc.).

## **Detect&Avoid: Conflict Traffic**



- Three layers for conflict management approach (as manned):
  - Strategic conflict management.
  - Separation provision (by ATC, Remain Well Clear RWC–).
  - Collision Avoidance: maneuver execution to resolve conflicts.



# **Detect&Avoid: MIDCAS Project**



- The system is composed by cooperative and not-cooperative mid-air collision avoidance system made up of:
  - Cooperative sensors:
    - 3 EO (Electro-Optical) and 4 IR (Infra-Red) sensors.
    - Electrical Scan Radar (Ku band, >0.5Hz refresh rate).
  - Non-Cooperative sensors:
    - ADS-B receiver.
    - IFF transponder.





# **Platform Technology**



- The need to allow extended mission capability of RPA requires:
  - A reduction of airframe structural weight.
  - Increased reliability.
  - Higher electrical power availability.
  - Increased endurance.
- Key enabling technologies are:
  - Composite: OOA (Out-Of-Autoclave) and ATL (Automatic Tape Layer).
  - Electro-mechanical actuators: High Reliable EMA.
  - Electric System: high voltage electrical power generation and modular distribution.
  - Propulsion System: high efficiency for long endurance, high altitude RPA.





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# **Payload Technology**

- Electro-optical sensors.
- Surveillance radar.
- Electronic surveillance sensors.
- Hyper-spectral sensors.









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#### Conclusions



- RPAS are a **new component** of aviation system and are based on cutting-edge development in aerospace technologies.
- The integration of RPAS into non-segregated airspace is a long-term activity, requiring advanced technology for DAA, C2 BRLOS as well as robust regulatory framework.
- Italy can play an important role in the **European technology non-dependence.**
- Piaggio Aerospace participation inside European Project (e.g. DeSIRE II) is contributing to a truly **European flagship** technology initiative on Air Traffic Insertion of RPAS.

# Thank you for your attention!

